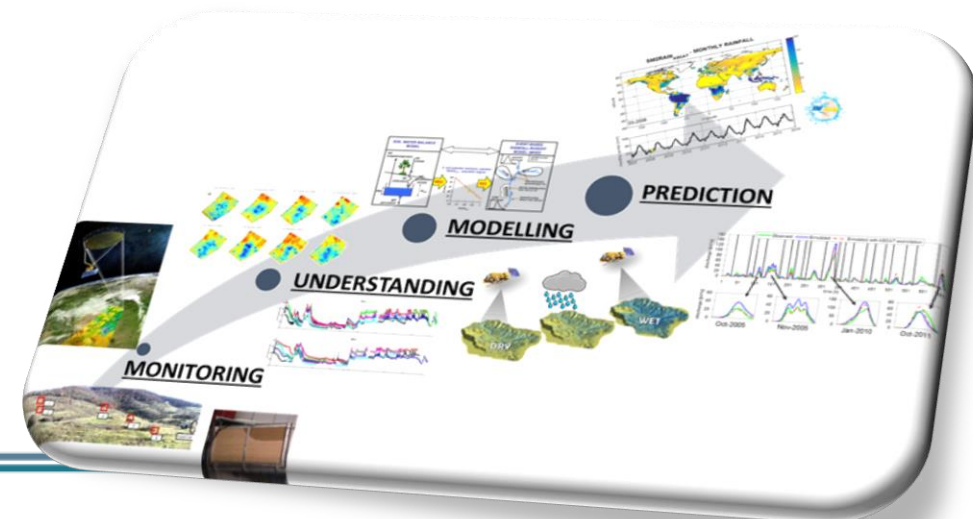


# H-SAF PRODUCTS APPLICATION SOIL MOISTURE FOR HYDROLOGICAL RISK MANAGEMENT

Rome, 13-16/11/2018

## SM data assimilation for flood prediction

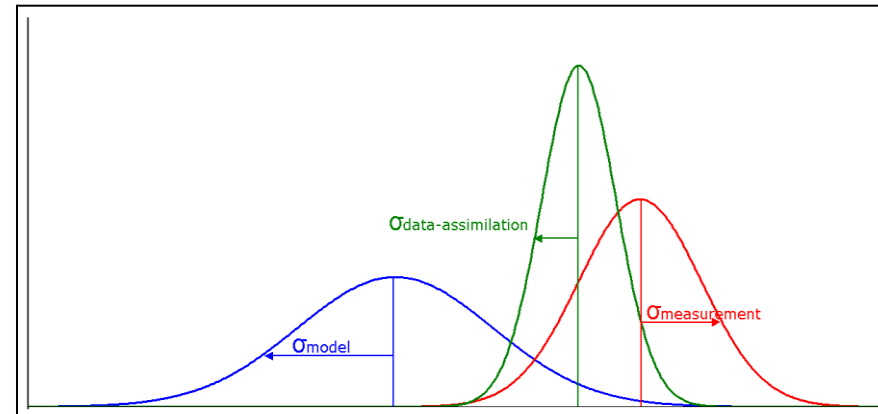
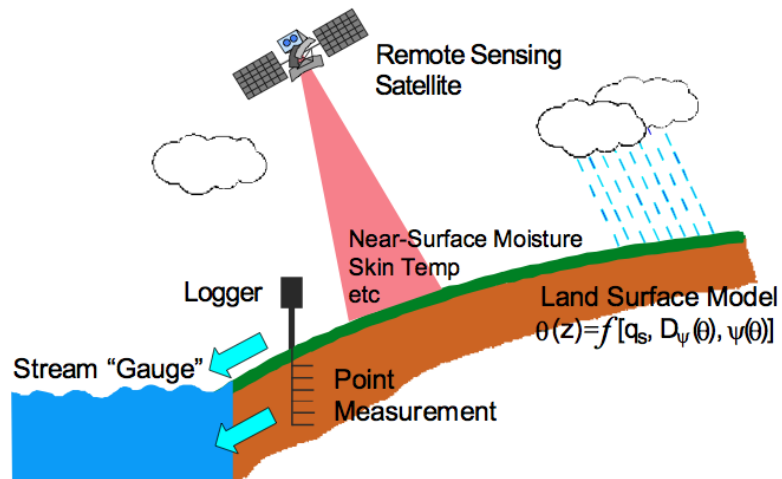
Simone Gabellani  
Fondazione CIMA

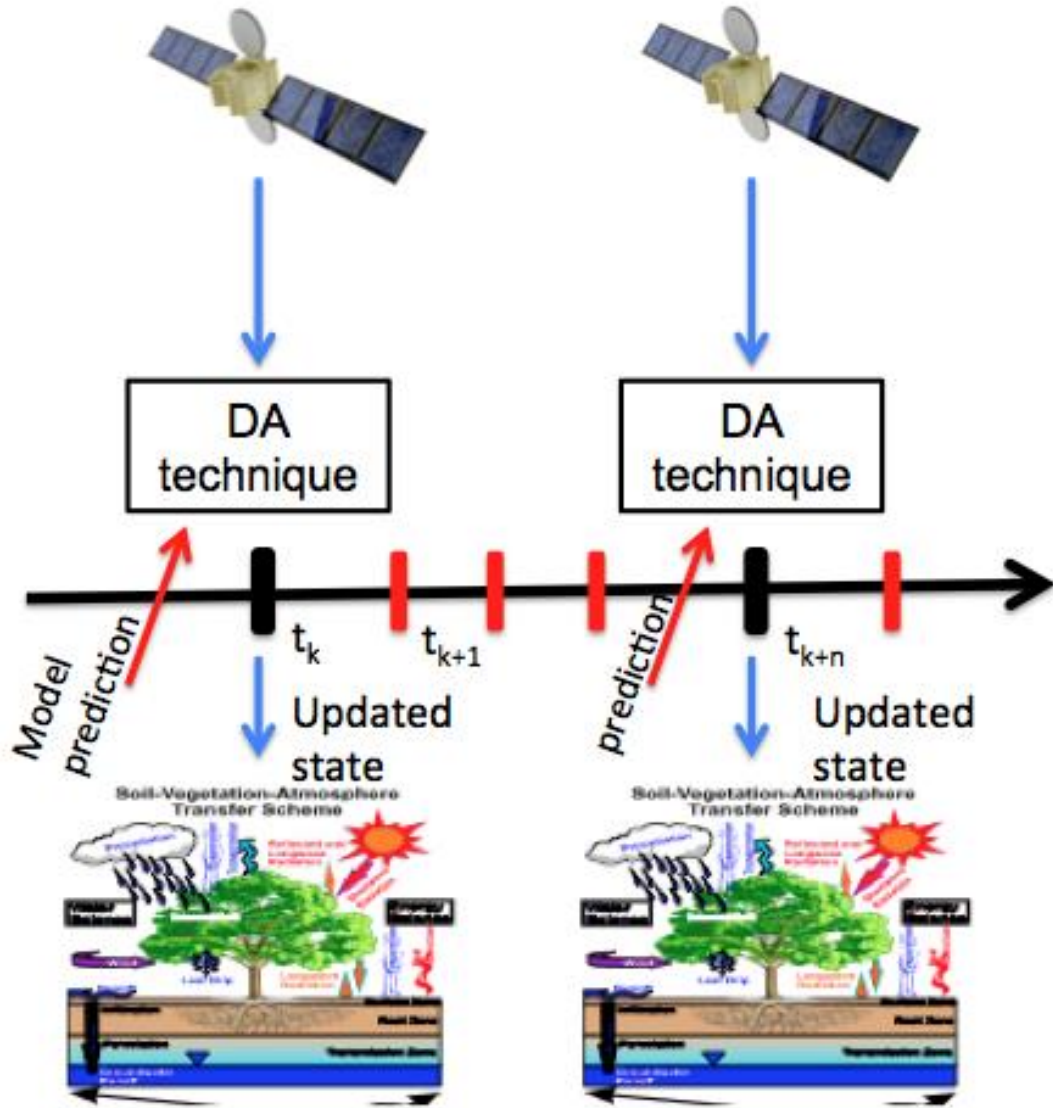


*Charney et al.* [1969] first suggested combining current and past data in an explicit dynamical model, using the model's prognostic equations to provide time continuity and dynamic coupling amongst the fields. This concept has evolved into a family of techniques known as data assimilation.

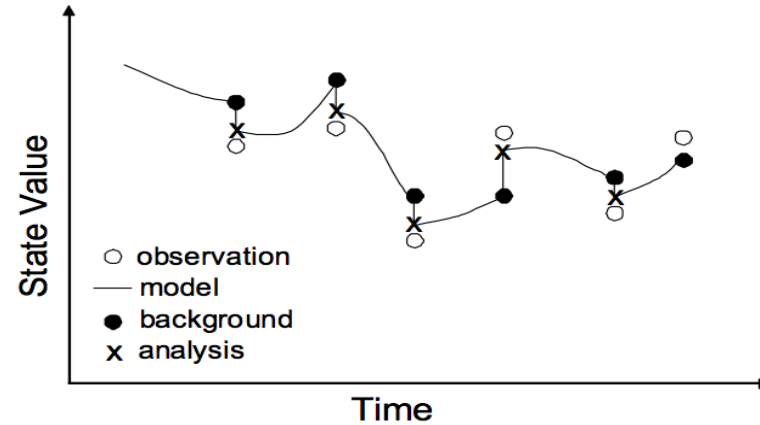
Data assimilation is used operationally in oceanography and meteorology, but in hydrology it is only recently that international research activities have been deployed.

In essence, hydrologic data assimilation aims to utilize both our hydrologic process knowledge as embodied in a hydrologic model, and information that can be gained from observations. Both model predictions and observations are imperfect and we wish to use both synergistically to obtain a more accurate result. Moreover, both contain different kinds of information, that when used together, provide an accuracy level that cannot be obtained when used individually.





Data Assimilation merges observations & model predictions to provide a superior state estimate.



### Measurement errors:

- Retrieval errors

### Model errors:

- Initialization error.
- Errors in atmospheric forcing data. Errors in model physics (model not perfect).
- Errors in representation (sub-grid processes).
- Errors in parameters (soil and vegetation)

# (some) Open questions in DA

1. Which is the best DA techniques?
2. How can satellite data be used in a framework for DA in hydrological models?
3. Which is the proper model configuration?
4. Which is the impact of DA on the hydrological cycle?

# Data Assimilation Technique

Direct insertion (Houser et al. 1998; Walker et al. 2001a)

Statistical correction (Houser et al. 1998)

Successive correction Bergthorsson and Döös (1955)

Analysis correction Lorenc et al. (1991)

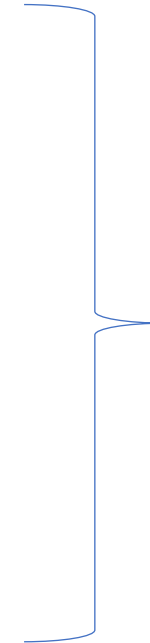
**Nudging** (Stauffer and Seaman 1990)

Optimal interpolation (Lorenc et al. 1991)

Kalman Filters, simple, extended, ensemble (Evensen)

Particle filter (Kalman, 1960; Evensen 1994, Gordon et al. 1993)

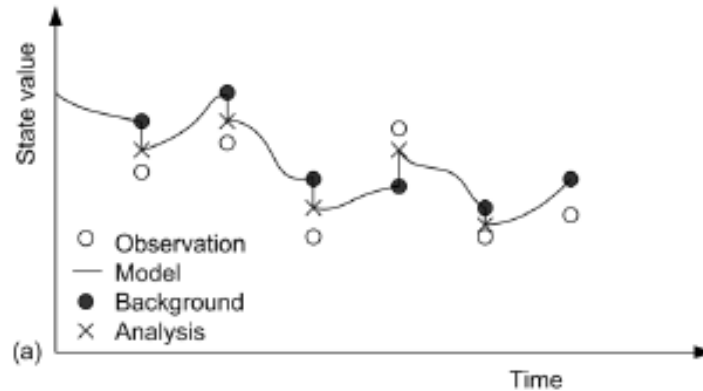
Variational (Reichle et al 2001, Liu and Gupta, McMillan et al 2013, Ercolani and Castelli 2017)



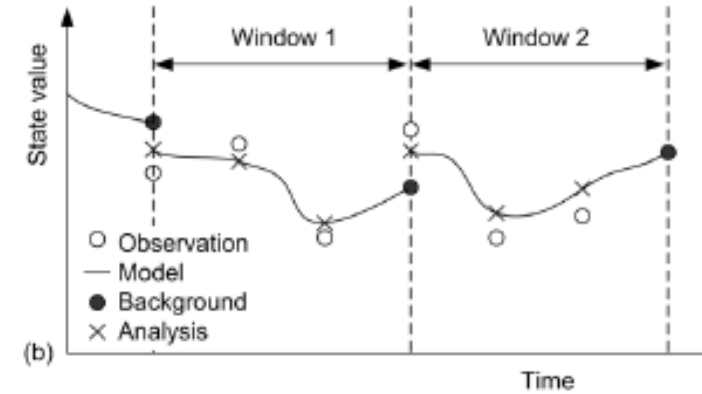
**Sequential**

**Houser, De Lannoy and Walker (2012).** Hydrologic Data Assimilation, Approaches to Managing Disaster - Assessing Hazards, Emergencies and Disaster Impacts, <http://www.intechopen.com/books/approaches-to-managing-disaster-assessing-hazards-emergencies-and-disaster-impacts/land-surface-data-assimilation>

## Sequential



## Variational



**Theoretically** given a model integration with finite time interval, and assuming a perfect model, 4D-Var and the Kalman filter yield the same result at the end of the assimilation time interval however:

- can deal with a wide range of model error
- Simple, flexible and more suitable for near real time applications
- Discontinuity in the correction – model shocks
- more optimal in the assimilation window
- more difficulties in including model error and more sensitive to the non linearity of the model
- considerable computational cost

## The assimilation technique is particularly important in some cases

Samuel, J. et al. 2014 (JoH)

“[...] In the streamflow assimilation, soil moisture states were markedly Distorted [...]”

”General filtering approaches in hydrologic data assimilation, such as the ensemble Kalman filter (EnKF), are **based on the assumption that uncertainty of the current background prediction can be reduced by correcting errors in the state variables at the same time step**. However, this assumption may not be valid when assimilating stream discharge into hydrological models to correct soil moisture storage **due to the time lag between the soil moisture and the discharge ...**”

Li et al. 2013 (WRR)

The EnKF is designed to update model-forecasted state predictions at the same time an observation is acquired. No attempt is made to reanalyze previous model predictions in response to a particular observation. In contrast, the **Ensemble Kalman Smoother (EnKS)** can be used to update all model states predictions within a fixed lag of past time (Dunne and Entekhabi, 2005). Crow and Ryu, 2009 (HESS)

# Nudging

$$SM_{mod}^+(t) = SM_{mod}^-(t) + K \cdot [SM_{obs}(t) - SM_{mod}^-(t)]$$

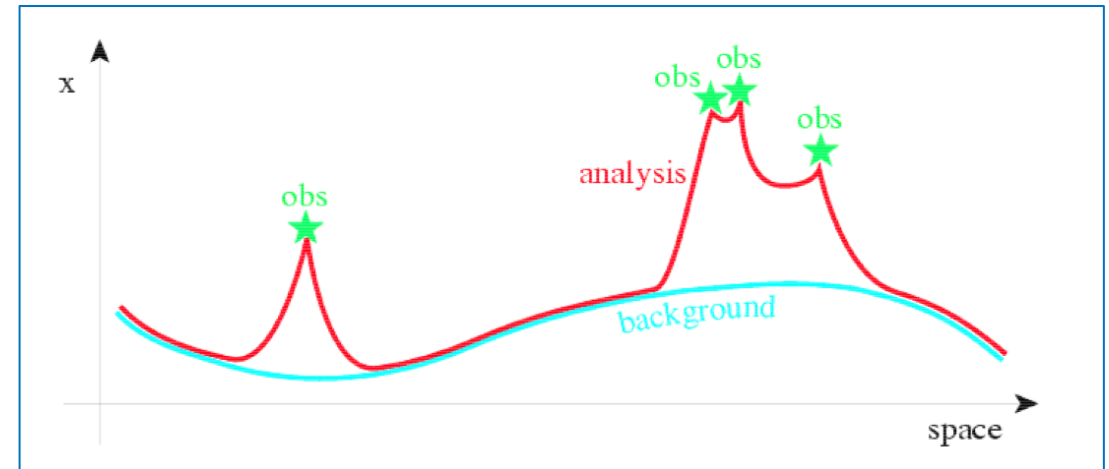
$SM_{obs}$ : observed SM

$SM_{mod}^-$ : background modelled SM

$K$  : gain, takes into account the uncertainties of both the model and the satellite observation

$$K = \frac{\sigma_{mod}}{\sigma_{mod} + \sigma_{obs}}$$

$SM_{mod}^+$ : updated modelled SM



One key question in the nudging data assimilation technique is the choice of the gain matrix  $K$ .

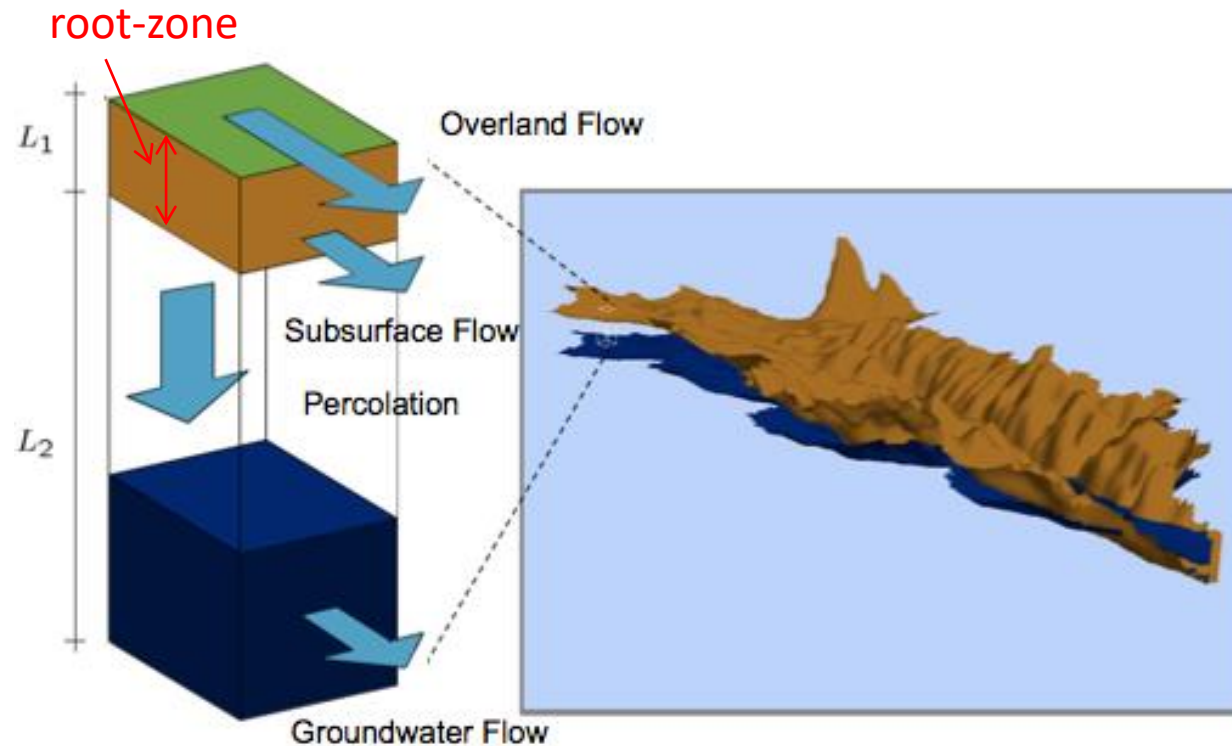
If  $K$  is equal to 1 the observations are assumed very reliable and modelled variable is replaced by the observation (direct insertion);

if  $K$  is equal zero no update is done.



# How can sat. data be used in DA?

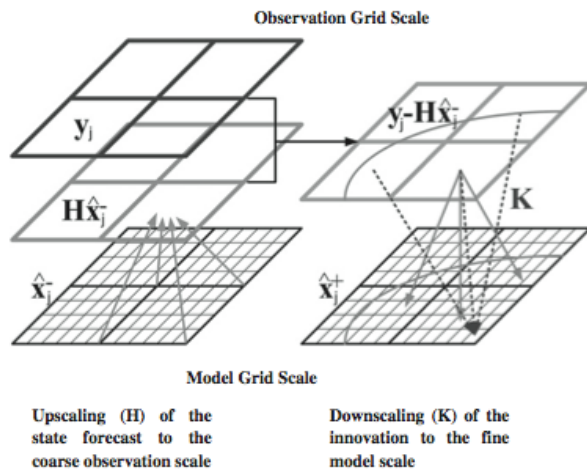
Satellite data give information of soil moisture for the first centimetres of the soil. This may not match the layer depth simulated by the model (different climatology and considerable bias)



Usually satellite soil moisture data **CANNOT** be directly used within hydrological models

# How can sat. data be used in DA?

- A. “Transform” the sat. SSM in the “same” modelled variable
- → **Filtering**
- B. Adjusting the observation to match the climatology of the model
- → **Bias handling**



Lumped and distributed model must be considerate in different way

Fig. 2. A schematic diagram of the 3-D EnKF approach illustrated for four coarse-scale pixels, each containing  $4 \times 6$  fine-scale pixels.

**Bias Handling:** Several potential strategies exist and have been applied in hydrologic data assimilation

**Variance matching (VM)** (Brocca et al. 2010, 2012, Matgen et al. 2011, Chen et al. 2011)

**Linear regression techniques (LR)**

**Cumulative distribution function matching (CDF)** (Reichle and Koster 2004)

**Anomaly based cumulative distribution (aCDF)**

**Triple collocation analysis-based approach (TCA)** (Stoffelen 1998, Yilmaz and Crow 2013)

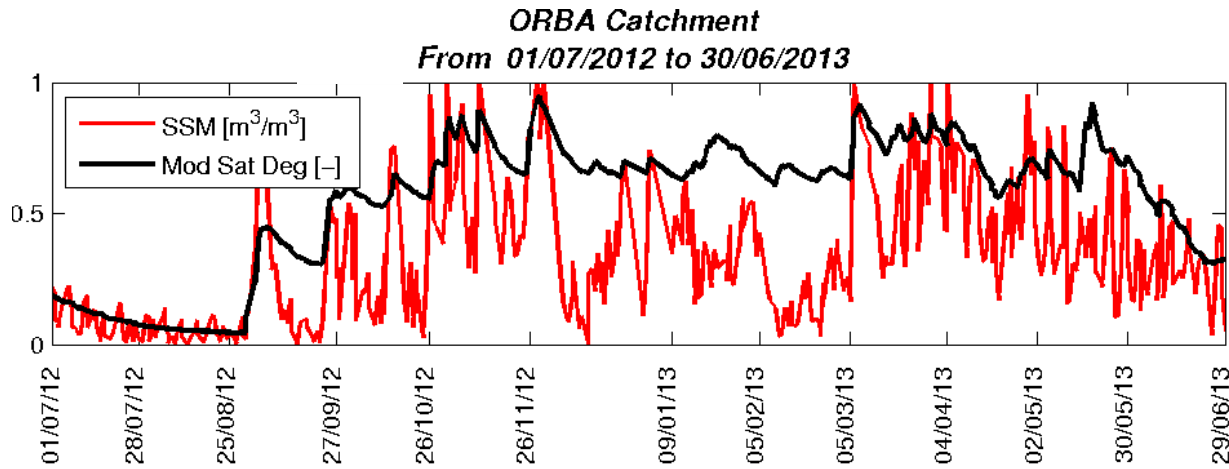
simple rescaling techniques may perform equally well to more complex ones

$$SAT^* = \frac{SAT - m(SAT)}{S(SAT)} \times S(SD_{mod}) + m(SD_{mod})$$

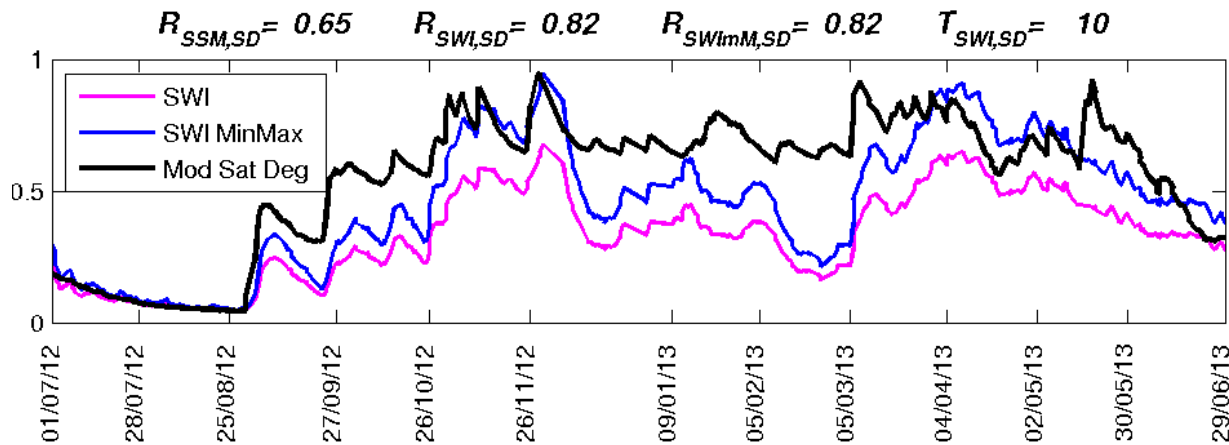
$$SAT^* = \frac{SAT - \min(SAT)}{\hat{e}_{\max(SAT) - \min(SAT)}}$$

$$\times \hat{e}_{\max(SD_{mod}) - \min(SD_{mod})} + \min(SD_{mod})$$

# How can sat. data be used in DA?



1. Filtering → SWI
2. Bias handling



$$SAT^* = \frac{SAT - m(SAT)}{S(SAT)} \times S(SD_{mod}) + m(SD_{mod})$$

$$SAT^* = \frac{SAT - \min(SAT)}{\max(SAT) - \min(SAT)}$$

$$\times \frac{\max(SD_{mod}) - \min(SD_{mod})}{\max(SD_{mod}) - \min(SD_{mod})} + \min(SD_{mod})$$

## Han et al., 2012

Synthetic experiments using SWAT model Results of assimilation:

- great impact on soil moisture
- small impact on discharge
- impact on discharge is a function of soil type
- the capability of the SSM assim. for improving streamflow is constrained by the accuracy of precipitation

## Massari et al., 2015

How the catchment area, soil type, climatology, rescaling technique, observation and model error selection may affect the results of the assimilation

- (i) DA of SM generally improves discharge predictions (with a mean efficiency of about 30%);
- (ii) unlike catchment area, the soil type and the catchment specific characteristics might have a remarkable influence on the results;
- (iii) simple rescaling techniques may perform equally well to more complex ones

Laiolo et al., 2016 - Cenci et al 2016

**Hydrological model:** Continuum (physically based distributed)

## Satellite Products

3 SM PRODUCTS DERIVED FROM ASCAT

SMOS SM PRODUCT

## Assimilation scheme:

1. NUDGING – MODEL SCALE
2. NUDGING – SATELLITE SCALE
3. ENSEMBLE KALMAN FILTER– MODEL SCALE

**modelled discharge with DA compared with:** Observed discharge and “Open Loop” run (without DA)



Fig. 1. Study areas. Overview of the catchments under investigation: OB (red), CS (light blue), and MG (purple).

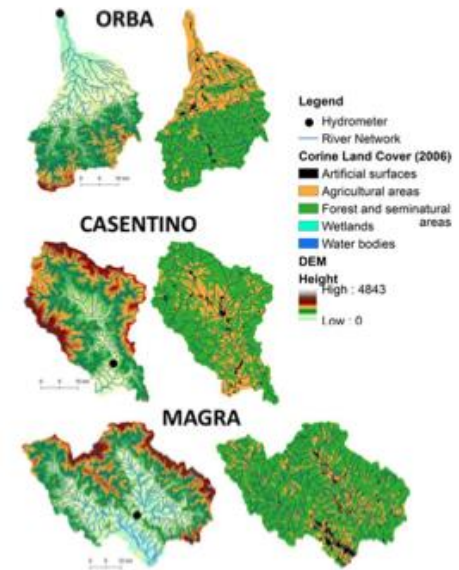
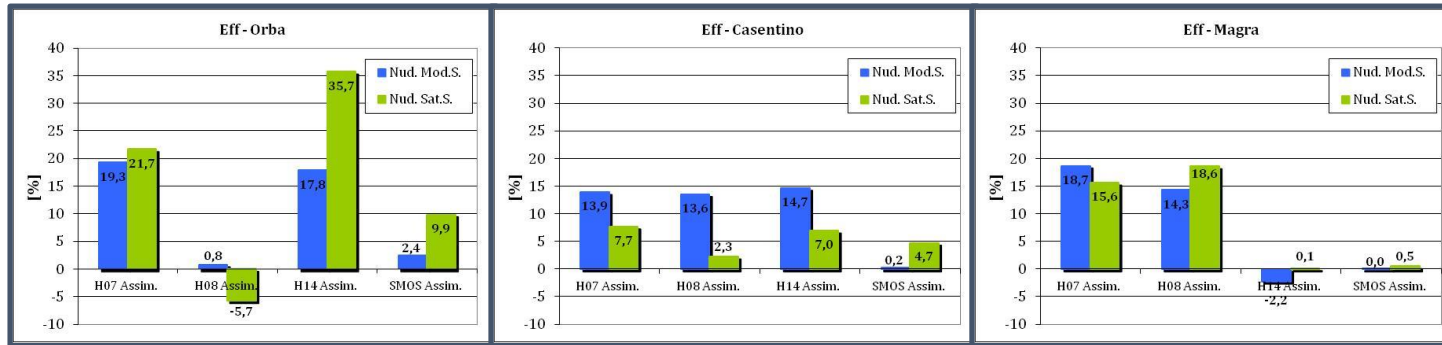
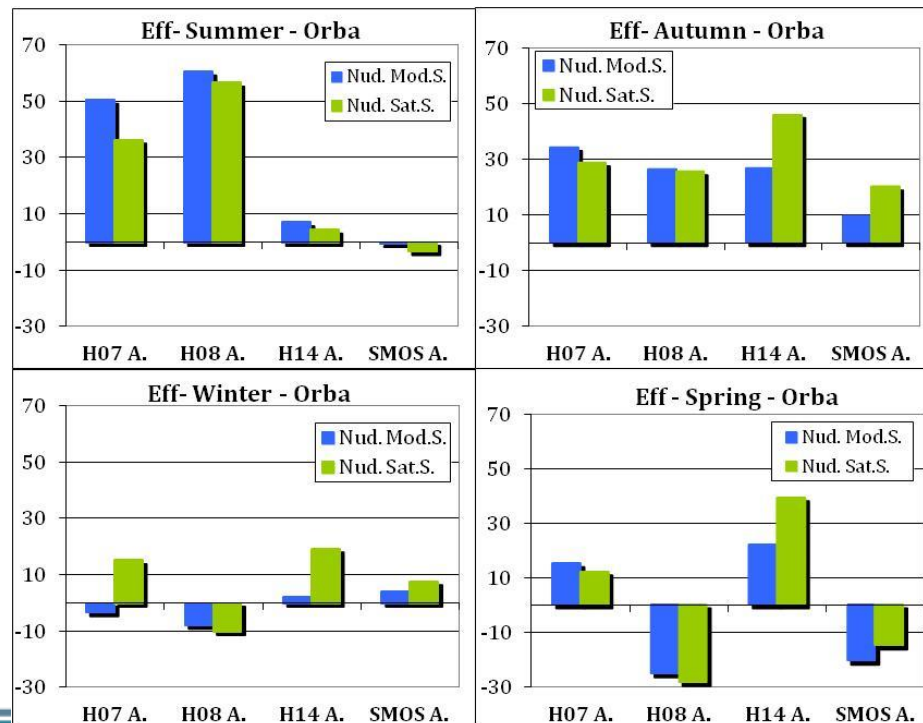


Fig. 2. Study areas: Details of the catchments under investigation: gauging stations (left column), the topography (left column), the Corine land cover—Level 1 (right column) and the hydrography (both columns).

# Which is the impact of DA on the hydrological cycle?

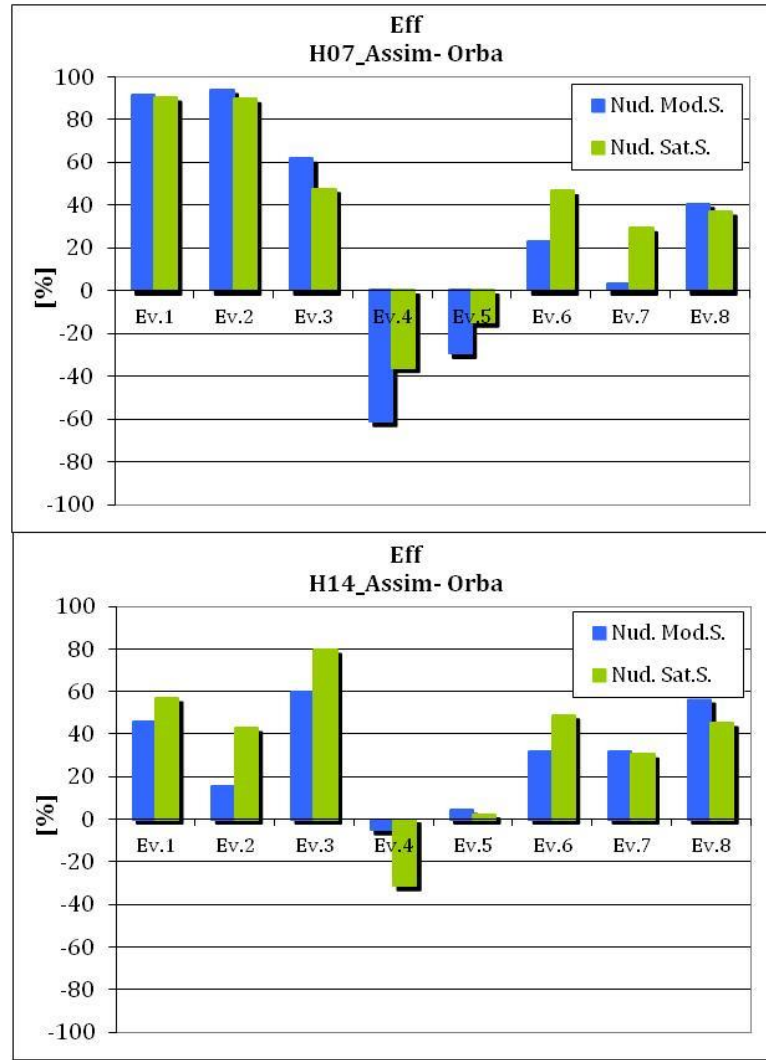
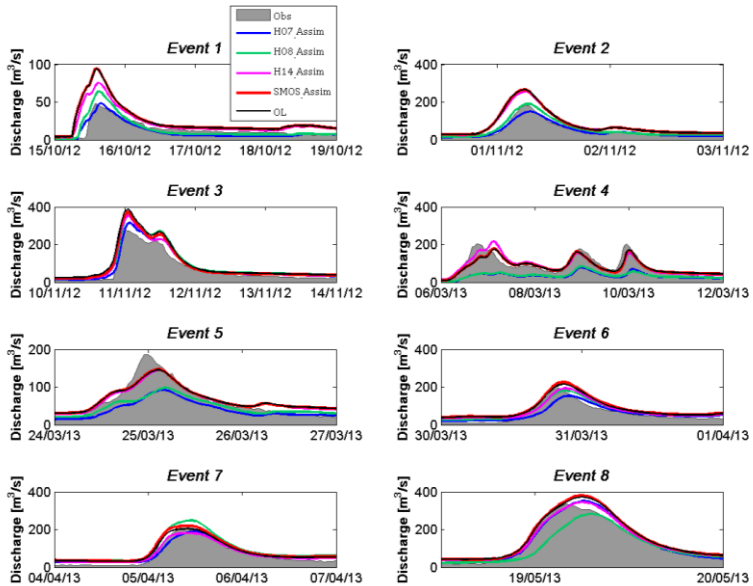


remotely sensed data could be used to update a physically-based, distributed hydrological model applied to a small catchment using a careful data elaboration and a **simple DA technique** which is easy to be applied for Civil Protection purposes in an operative flood forecasting framework.



improvements of SM assimilation were high especially in **summer and autumn** while in winter some problems occurred.

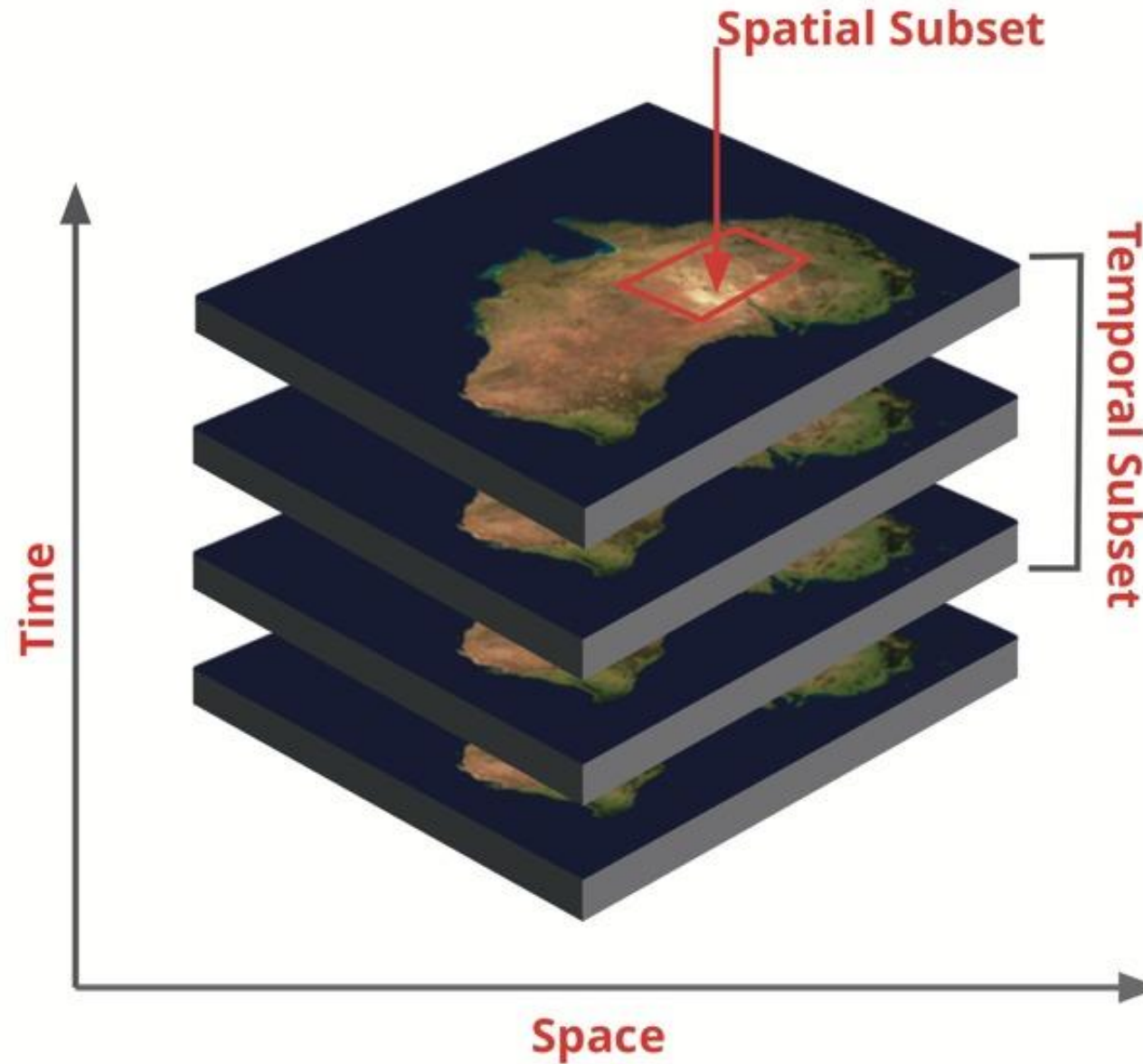
# Which is the impact of DA on the hydrological cycle?



Moreover, the positive results of the assimilation experiments allow to conclude that, similarly to what found in Wanders et al., 2014, satellite data could be used to improve the model performance for ungauged basins



# Introduction to the exercise

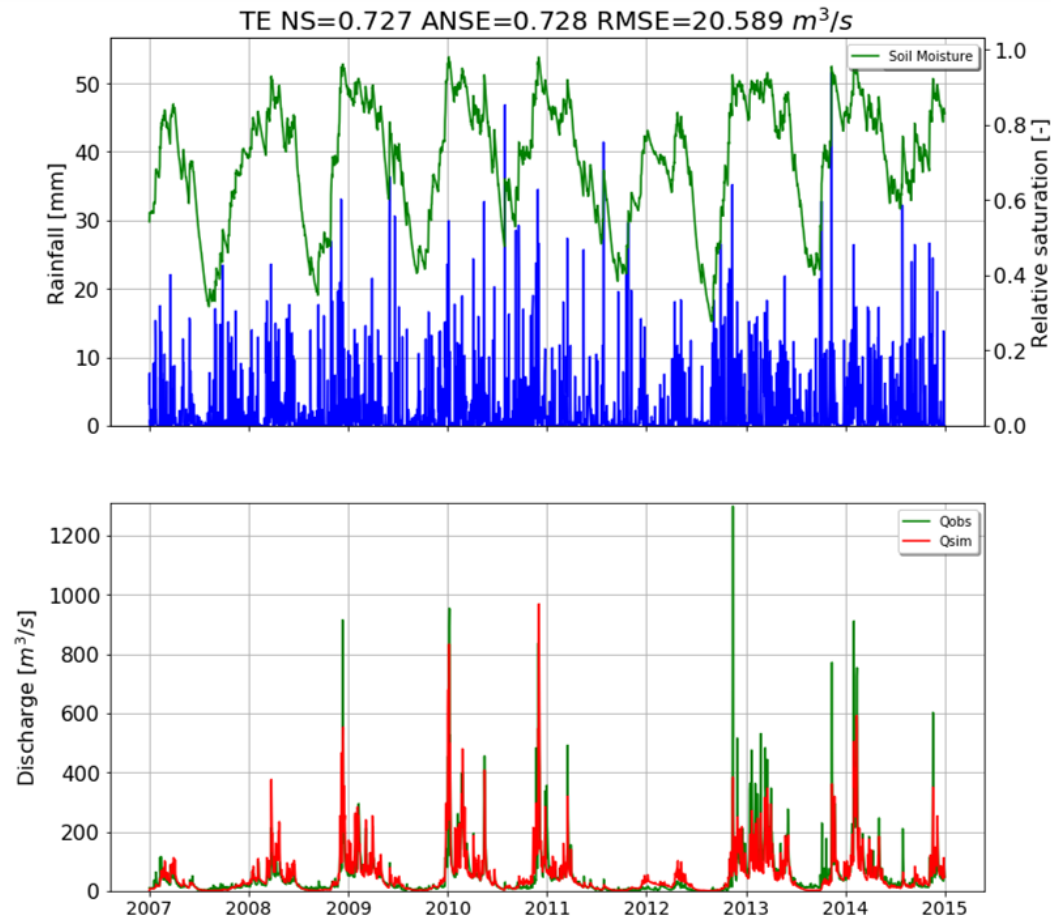


**EACH STEP SHOULD BE ANALYSED AND DISCUSSED (briefly)**  
**RESULTS SHOULD BE DONE WITH THE TWO SOIL MOISTURE PRODUCTS (ASCAT and ASCAT+ECMWF)**

- Assimilation of SM in the rainfall-runoff modelling (IRPI's code) in WG basins with different values of K [0.1, 1]
- Comparison between observed and simulated discharge for the different K
- Comparison between observed and simulated soil moisture for the different K

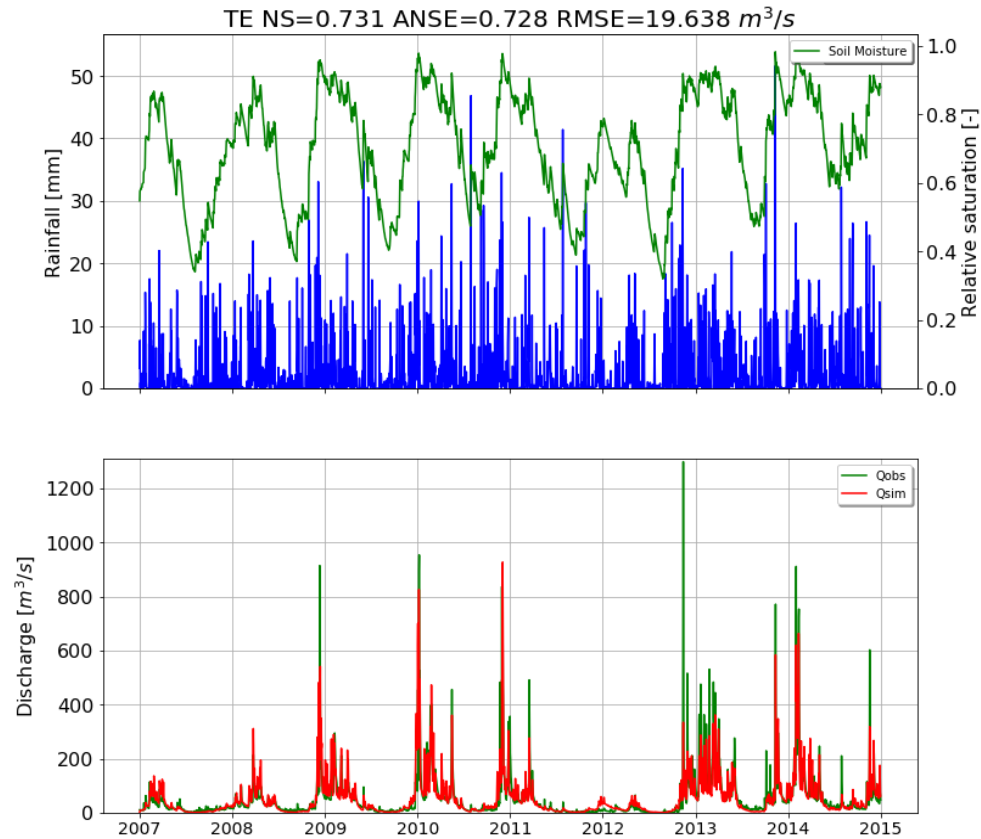
Assimilation of SM in the rainfall-runoff modelling in WG basins with different values of G [0, 0.1]

Open loop run

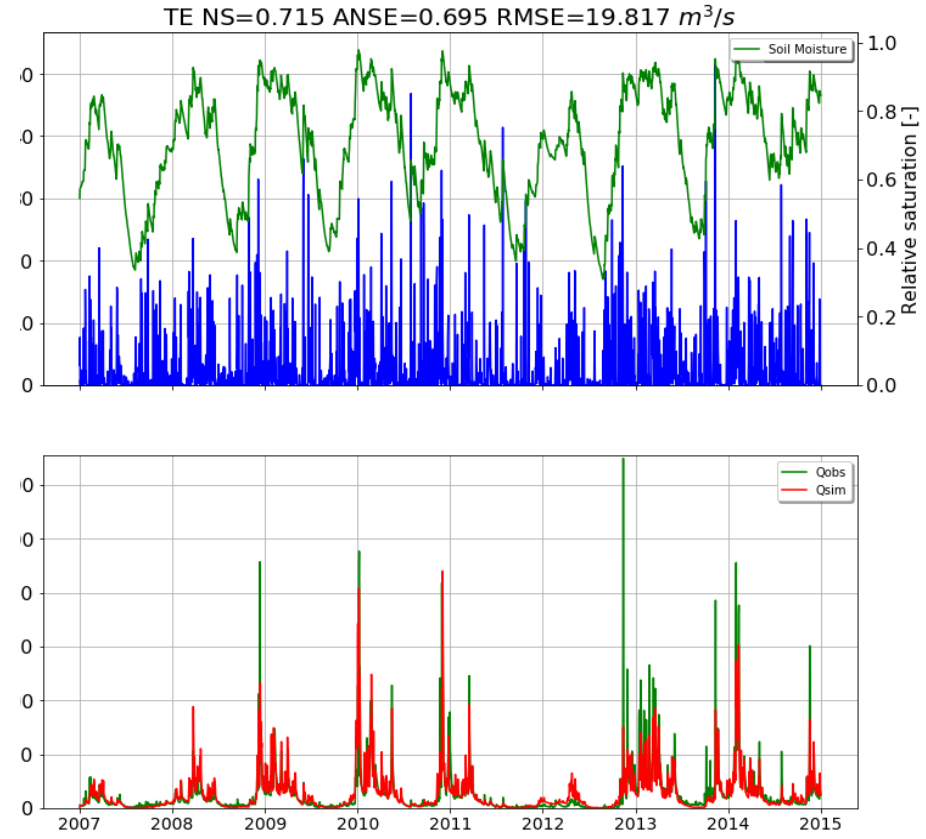


Comparison between observed and simulated discharge with value of  $G = 0.02$

H113 SWI 30

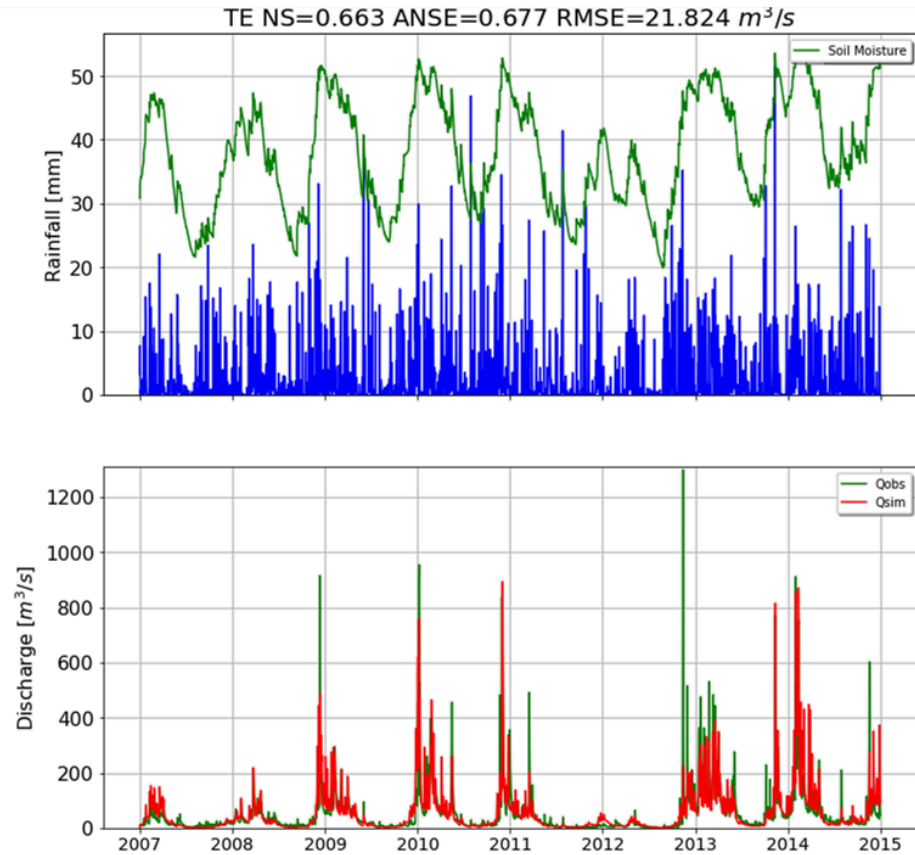


H27 layer 3



Comparison between observed and simulated discharge with value of  $G = 0.1$

H113 SWI 30



H27 layer 3

